Align-RUDDER: Learning From Few Demonstrations by Reward Redistribution



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Align-RUDDER in a Nutshell





demo 1 demo 2 demo 3 demo 4 demo 5 demo 6 consensus





Complex Tasks have Delayed Rewards

Complex tasks often have episodic rewards:

- Actions cause reward or penalty that is obtained much later
- Distracting rewards may be present
- Credit assignment problem: which action was responsible?



CHAPTER I

INTRODUCTION

The credit-assignment problem for a complex learning system (Minsky, 1961) is the problem of properly assigning credit or blame for overall outcomes to each of the describing system's increase significant that see this work in the theorem is a second sec





The Problem of TD and MC

- Traditional approaches make guesses about the future
- Correcting the bias of temporal difference (TD) learning (SARSA and Qlearning) requires exponential updates
- Monte Carlo (MC) methods have high variance since variance is propagated through all states that are visited





Detecting Key Events

- Analyze episodes that have been observed
 - No probabilities and no guesses about the future
 - Detect key events that lead to rewards (i.e. sub-goals)
- Supervised learning problem
- Example: RUDDER [2]





RUDDER: Reward Redistribution to Key Events

- Give immediate feedback
- Reward is the difference in the expected return (RUDDER [2])
- Reduces the delay of rewards
- Identifies key events and landmarks







Few Demonstrations

- Often only few expert demonstrations available
- Training an LSTM model...
 - ...is difficult from a small number of demonstrations
 - ...requires high and low return examples





Sequence Alignment for Reward Redistribution

- Sequence alignment works with a **small number of examples**
- Sequence alignment uses only closely related examples
- The result of such an alignment is a profile model
- New sequences are aligned to a profile model and receive an **alignment score**
- The redistributed reward is proportional to the difference of scores of consecutive time steps





I) Defining Events



II) Scoring Matrix



III) Multiple Sequence Alignment



IV) PSSM and Profile



V) Reward Redistribution





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Mining a Diamond in Minecraft



















(II) Determine the Scoring Matrix

Event







(III) Multiple sequence alignment (MSA)





(III) Multiple sequence alignment (MSA)





(IV) Position-specific Scoring Matrix





(IV) Position-specific Scoring Matrix





(IV) Reward Redistribution





(IV) Reward Redistribution





(IV) Reward Redistribution







Experiments: Gridworld



Example of a reward redistribution in a grid world with four rooms



Example of a reward redistribution in a grid world with eight rooms





Comparison of Align-RUDDER to other methods with respect to the number of episodes required for learning on different numbers of demonstrations

Experiments: Minecraft

- First pure learning method to obtain a diamond in the MineRL environment
- Only 10 demonstrations were necessary to identify key events
- Hierarchical RL of sub-agents identified using reward redistribution

Method	Team Name		7	7		N	
Align-RUDDER	Ours						
DQfD	CDS						
BC	MC_RL						
CLEAR	I4DS						
Options&PPO	CraftRL						
BC	UEFDRL						
SAC	TD240						
MLSH	LAIR						
Rainbow	Elytra						
PPO	karolisram						



Contributions



 ⁽/₄): <u>https://twitter.com/wehungpatil</u>
 ⁽/₄): <u>https://twitter.com/mrkhof</u>
 ⁽/₄): <u>https://arxiv.org/abs/2009.14108</u>
 ⁽/₄): <u>https://arxiv.org/abs/2009.14108</u>
 ⁽/₄): <u>https://ml-jku.github.io/align-rudder</u>
 ⁽/₄): <u>https://github.com/ml-jku/align-rudder</u>
 ⁽/₄): <u>https://github.com/ml-jku/align-rudder</u>
 ⁽/₄): <u>https://tinyurl.com/2p8cdrfk</u>



- We suggest a reinforcement algorithm that works well for sparse and delayed rewards, where standard exploration fails
- We adopt **multiple sequence alignment** from bioinformatics to construct a reward redistribution technique that works with **few demonstrations**
- We propose a method that uses alignment techniques and reward redistribution for identifying sub-goals and sub-tasks which in turn allow for hierarchical reinforcement learning

[1] R. S. Sutton, 'Temporal Credit assignment in Reinforcement Learning', 1984

[2] Arjona-Medina et. al, 'RUDDER: Return decomposition for delayed reward', 2019

[3] Guss et. al, 'The MineRL 2019 Competition on Sample Efficient Reinforcement Learning using Human Priors', 2019